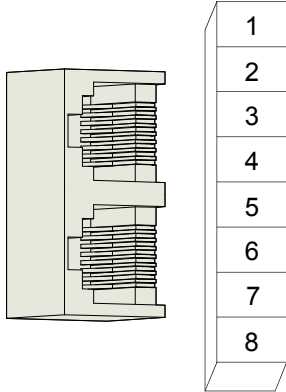


Table 3-28 Pin definition of communication signal terminal connectors

| Pin No. | Pin | Description | Pin Layout |
|---------|-----------|---|---|
| 1 | CANH | CAN communication port |  |
| 2 | CANL | | |
| 3 | CGND | CAN communication ground | |
| 4 | RS485+ | RS485 communication port | |
| 5 | RS485- | | |
| 6 | RS232-TXD | RS232 transmitting end, connected to the receiving end of the host controller | |
| 7 | RS232-RXD | RS232 transmitting end, connected to the sending end of the host controller | |
| 8 | GND | Ground | |
| Housing | PE | Shield | |

3.5.2 CAN Communication Connection

CAN Communication Connection with PLC

The following figure shows the cable connection between the servo drive and the PLC under CAN communication.

Figure 3-19 Appearance of communication cable between servo drive and PLC



Table 3-29 Pin definition of communication cable between servo drive and PLC

| RJ45 on Servo Drive Side (A) | | | PC Side (B) | | |
|------------------------------|-------------|---------|-------------|-------------|---------|
| Type | Signal | Pin No. | Type | Signal | Pin No. |
| CAN | CANH | 1 | CAN | CANH | 1 |
| | CANL | 2 | | CANL | 2 |
| | CGND | 3 | | CGND | 3 |
| | PE (shield) | Housing | | PE (shield) | Housing |

CAN Communication Connection for Multi-drive Use

The following figure shows the cable connection between multiple servo drives under CAN communication.